TOBB UNIVERSITY OF ECONOMICS AND TECHNOLOGY GRADUATE SCHOOL OF ENGINEERING AND SCIENCE

CLASSIFICATION OF ELECTRONIC DEVICES USING HARMONIC RADAR BASED ON A LINEAR MODEL WITH POWER-SWEPT SIGNALS

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Maryam Shahi



ABSTRACT

Master of Science Thesis

CLASSIFICATION OF ELECTRONIC DEVICES USING HARMONIC RADAR BASED ON A LINEAR MODEL WITH POWER-SWEPT SIGNALS

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Date: July 2019

Nonlinear circuit components such as diodes, transistors, etc. receive a transmitted signal at a fundamental frequency and re-radiate the harmonics and possibly intermodulation products of that frequency. Many studies have been done to utilize nonlinearities of electronic circuits to detect, range, and track targets of interest in the presence of clutter using harmonic radar, yet only a few number of researches focus on classification of various electronic circuits.

A new technique to use nonlinear characteristics of electronic devices for classification of those devices using Harmonic Radar is proposed in this thesis. Unlike prior work in the literature, the powers of the transmitted incident waves are swept within a determined range in this study to capture the nonlinearities of the Electronic Circuits Under Test (ECUT). National Instruments (NI) AWR Design Environment is used to design the ECUT of this study. The first three harmonics of the received powers are analyzed in harmonic space. This novel method, derives the harmonic responses of the ECUT using Power Series Model. As a major contribution of this research, a linear model is proposed to relate the measurements to the unknown deterministic vectors of parameters characterizing the nonlinearities of the ECUT.

Each electronic circuit under test has a distinguishable harmonic response to a single-tone or two-tone incident wave with varying power. Therefore, a unique vector

of parameters can be derived from the presented linear model for each circuit. A Maximum Likelihood Estimator (MLE) is used in this novel approach to estimate the unique vectors of parameters in the presence of Complex White Gaussian Noise (CWGN) based on the newly developed linear model. K-Nearest Neighbors (kNN) classification method is employed to classify different nonlinear electronic devices such as diode clamper, diode limiter, and full-wave rectifier using the statistical features of the normalized estimated vectors of parameters as distinguishing factors. Simulation results prove the presented method of power-swept incident waves and estimated vectors of parameters to be an effective approach for classification of nonlinear devices using harmonic radar. The performance of the normalized estimated vectors of parameters and scattered feature plots of the normalized estimated vectors of parameters. It is shown that the presented classifier in this study has a better performance compared to existing classifiers.

Keywords: Harmonic radar, Power series model, Maximum likelihood estimator, Linear model, K-nearest neighbors, Classification, Vectors of parameters

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ABBREVIATIONS

ECUT	: Electronic Circuits Under Test
MLE	: Maximum Likelihood Estimator
CWGN	: Complex White Gaussian Noise
KNN	: K-Nearest Neighbors
RF	: Radio Frequency
FM	: Frequency Modulation
BPSK	: Binary Phase-Shift Keying
MSE	: Mean Square Error
SNR	: Signal-to-Noise Ratio
XFMRTAP	: Ideal Transformer with Center Tap
SWPVAR	: Swept Variable Control
PDF	: Probability Density Function
LS	: Least Squares



1. INTRODUCTION

1.1 Review of Literature

Linear systems satisfy the principle of superposition (homogeneity and additivity properties) [1]. A system that does not meet the principle of superposition, is called a Nonlinear System. A circuit component that shows nonlinearities is considered a nonlinear system by definition.

A harmonic radar system works by transmitting a signal to a nonlinear target of interest which receives the signal at a fundamental frequency and generates harmonics and possibly intermodulation products of that frequency [2]. The harmonics are then re-radiated back to the receiver. A harmonic radar is able to distinguish between nonlinear "targets" and "clutter" (other objects that generate false alarms if driven by an incident wave) [3]. Therefore, nonlinearities of the electronic circuits can be utilized as important distinguishing features since natural clutter only re-radiate the fundamental frequencies of the transmitted wave.

Many open-air experimental setups have proved that RF devices generate harmonics of the fundamental frequencies and multitone products of those frequencies [4]. Certain circuit components such as diodes, semiconductors, transistors, etc. can be discriminated by studying the re-radiation of those components at harmonic frequencies of the incident waves. Some of the RF circuit elements such as amplifiers show unwanted nonlinear properties that can distort the received signals form the target [5–7]. Many researches have been done to linearize the amplifiers in the transmitter to eliminate the unintended distortions [8–10]. The natural clutter do not show nonlinearities if driven by a harmonic radar [11]. Therefore, nonlinear characteristics of circuit components can be utilized to detect, track and classify

nonlinear circuits using harmonic radar. It has been shown that nonlinear circuits re-radiate the harmonics of the fundamental frequencies very poorly [12]. Thus, the preliminary shortcoming of the harmonic radar is the low received power at harmonics of the fundamental frequencies which in turn requires high transmitted power. Main purpose of this thesis is to analyze the re-radiated waves from various nonlinear circuits to derive the unique vectors of parameters based on a newly developed linear model to be used for classification of those circuits.

Detection of nonlinear targets of interest using harmonic radar technology has been issued in previous research numerously. For instance, a harmonic radar detects a non-linear moving target using Range-Doppler plots in [13]. A new approach is revealed by considering two unique sets of FM noise signals using harmonic radar to detect the multitone response of the device under test [14]. A novel detection method uses a binary phase-shift keying (BPSK) modulated signal to reduce the required transmitted power in a harmonic radar system [15]. Furthermore, many researches have been done to detect hidden electronic devices and man-made targets for military purposes [16–19].

The vast applications of harmonic radar technology are not limited to the detection of nonlinear targets. As an example, a multi-frequency radar detects and characterizes human activities using Doppler measurements in [20]. Vital signs have been successfully detected using a harmonic radar system in which the detection performance is improved by adding a phase shift between transmitted waves at two distinct frequencies [21]. A harmonic radar monitors the vital signs by analyzing first and second order harmonics of the incident wave to create frequency diversity [22]. One of the interesting applications of nonlinear radar technology is to observe bees' behavior using a transponder. Fast disappearance of worker bees can cause shortage of food all over the world. As a result, observing bees' behavior patterns has garnered significant attention to itself during the past decade [23–25]. Harmonic re-radiation of circuit components makes it possible to use harmonic radar for tracking tagged insects as well [26, 27]. Pest management has been a very crucial issue recently. Therefore, studying insect dispersal in the field using harmonic radar can offer effective solutions

to the issue.

The harmonic re-radiation of nonlinear targets is considered in [28]. As a popular technique in harmonic radar, single-frequency signals are transmitted to the targets in many researches [29]. Then, the harmonics of the transmitted frequencies are analyzed in the receiver to detect, track and distinguish the targets [30]. Two-tone incident waves are also transmitted to the targets to analyze the nonlinear characteristics of the targets in previous work [2, 31, 32]. Both single-tone and two-tone incident waves are utilized in this thesis to derive the unique signature of each electronic circuit to be used in classification of three different circuit types. First three harmonics of the re-radiated waves are analyzed in harmonic space. The re-radiated wave from a nonlinear circuit to a two-tone incident wave contains not only the harmonics of the fundamental frequencies but also the intermodulation products of those frequencies.

As summarized above, detecting, ranging and tracking of various targets and electronic devices have been included in the prior research [29, 33–37], yet only a few number of studies focus on classification of various electronic circuits using harmonic radar. A classifier is required to distinguish between the targets based on particular features. Harmonic re-radiations of nonlinear circuits can be utilized as a distinguishing feature vector in classification [38]. The harmonic responses of various nonlinear circuits to an incident wave with varying power are analyzed in [39]. The statistical features of harmonic re-radiations are used to distinguish between nonlinear devices. In another study, the Fourier analysis of the harmonic radar [40]. However, the novel approach in this thesis classifies various nonlinear electronic circuits such as diode clamper, diode limiter and full-wave rectifier based on a newly developed linear model and estimation of unknown deterministic vectors of parameters. Derivation of unique vectors of nonlinear model makes an important progress in classification of nonlinear circuits using harmonic radar.

National Instruments (NI) AWR Design Environment is used to design the ECUT of this study. First, single-tone and two-tone sinusoidal incident waves with varying power from 0 to 40 dBm with 1 dB intervals at 1 GHz frequency are used as the inputs

to all circuits under test. Unlike the previous research, sweeping the transmitted power in a determined range captures the nonlinear characteristics of the devices. Later, the first three harmonics of the output powers are analyzed in harmonic space. As a major contribution of this study, the re-radiated waves from the electronic circuits are calculated using power series model. The harmonic responses of the nonlinear circuits to power-swept single-tone and two-tone incident waves are derived for the first three harmonics of the fundamental frequencies and intermodulation products of those frequencies.

As a first in this area, a linear model is constructed in this study to relate the AWR measurements to the vectors of unknown parameters characterizing the nonlinearities of the ECUT. The observation matrices and unknown deterministic vectors of parameters are derived for both single-tone and two-tone re-radiation cases based on the newly developed linear model. Then, the vectors of parameters are estimated with a Maximum Likelihood Estimator (MLE) in the presence of Complex White Gaussian Noise (CWGN) for different SNR values using Monte Carlo simulations. The performance of the estimator is evaluated by analyzing the Mean Square Error (MSE) functions for one of the three main circuit types under test, diode clamper circuits. The normalized estimated vectors allow us to have the unique signature of each electronic device that makes it distinguishable from other devices.

As a novel technique, the statistical features of the normalized estimated vectors of unknown parameters are used as test and training data in classification of the ECUT using a kNN classifier. We categorize the data points in three main classes in kNN classification algorithm. First, kNN classifier calculates the Euclidean distances between test and training data sets. Then, it finds the k nearest neighbors and classifies the new devices into three device classes based on smallest Euclidean distances [41]. The proposed linear model in this thesis provides us with valuable information for classification of nonlinear devices since the statistical features of the normalized estimated vectors of parameters differ significantly for different nonlinear electronic devices. Visual and numeric evaluation of the novel method of this study at first, second and third order harmonics of the estimated vectors proves the latter statement.

1.2 Purpose of Thesis

Main purpose of this thesis is to classify various nonlinear devices such as diode clamper, diode limiter, and full wave rectifier by analyzing the re-radiated signals from those devices based on a newly proposed linear model. Nonlinearities of the ECUT are utilized as distinguishing factors in classification. The novel method of this study derives the first three harmonics of the re-radiated waves from the ECUT based on power series model for single-tone and two-tone re-radiation cases. Then, a linear model relates the measurements to the re-radiated waves from the ECUT by deriving the observation matrices and vectors of unknown parameters. Later, a Maximum likelihood estimator is employed to estimate these vectors in the presence of CWGN using Monte Carlo simulations. The statistical features of the normalized estimated vectors of unknown parameters are unique for each electronic device under test. Therefore, our ultimate goal is to use these vectors to distinguish and classify various nonlinear devices using kNN classification approach.

1.3 Organization

The further organization of this thesis is as follows. Harmonic re-radiation of a nonlinear device is discussed in Chapter 2. Power Series Model is given in Chapter 2.1 to calculate the input-output relationship of an electronic circuit. The re-radiated signals from a nonlinear device to single-tone and two-tone incident waves are predicted using Power Series Model in Chapter 2.1.1 and 2.1.2, respectively. The power series coefficients are also derived in Chapter 2.1.1 and 2.1.2 for first three harmonics and intermodulation products of fundamental frequencies for both single-tone and two-tone re-radiation cases. Experimental design and simulation of the ECUT are done using National Instruments (NI) AWR Design Environment in Chapter 2.2.

A linear model is proposed in Chapter 3 to relate the AWR measurements to the unknown deterministic vectors of parameters characterizing the nonlinearities of the ECUT. Chapter 3.1 gives the model description of the proposed method. The re-radiated waves from nonlinear devices under test are also re-written in Chapter 3.1 based on the newly constructed linear model in order to derive the vectors of parameters. The observation matrices and unknown deterministic vectors of parameters are derived in Chapter 3.2.1 and 3.2.2 for single-tone and two-tone re-radiation cases, respectively. Maximum likelihood estimation of the vectors of unknown parameters is included in Chapter 3.3. The performance of the estimator is also evaluated in Chapter 3.3 by plotting the Mean Square Error (MSE) functions with respect to SNR values for diode clamper circuits under test. The k-NN classification method is used in Chapter 3.4 for classification of the ECUT using normalized estimated vectors of parameters for both single-tone and two-tone re-radiation case are also given in Chapter 3.4 for single-tone re-radiation case to validate the proposed technique.

Performance evaluation and simulations results are discussed in Chapter 4. Single-tone and two-tone re-radiation results are analyzed using confusion matrices and scattered feature plots of the normalized estimated vectors of parameters in Chapter 4.1 and 4.2, receptively. Finally, Chapter 5 gives the conclusion of the research and future work.

2. HARMONIC RE-RADIATION OF A NONLINEAR DEVICE

The main goal of this study is to classify various electronic circuits using nonlinear characteristics of those circuits. To achieve that goal, a system model is needed that can predict the response of the nonlinear circuits under test to any input signal. The re-radiated signals from nonlinear devices cannot be described by a linear system model. Therefore, a nonlinear system model is utilized to formulate the re-radiation of a nonlinear device.

2.1 Power Series Model

The input-output relationship of a nonlinear electronic circuit do not satisfy the linearity property since nonlinear devices receive the transmitted signal at a fundamental frequency and re-radiate a new signal at harmonics and possibly intermodulation products of that frequency. The harmonic response of a nonlinear device to any incident wave can be predicted by *Power Series Model* [38], [42–46],

$$s[n'] = \sum_{n=1}^{\infty} s_n = \sum_{n=1}^{\infty} a_n x^n$$
 (2.1)

where *s* is the re-radiated signal from the device, *n* denotes the number of the harmonics of the fundamental frequencies, n' denotes the number of the received samples, *x* is the incident wave and a_n 's are the complex power series coefficients. According to this model, the re-radiated signal is equal to the sum of the incident wave raised to the nth power scaled by the power series coefficients. First three harmonics of the re-radiated waves from a nonlinear device are derived in two subsections for single-tone and two-tone re-radiation cases.

2.1.1 Single-Tone Re-Radiation

In case of a sinusoidal incident wave that contains only a single frequency, we have

$$x_1 = x_0 \sin(\omega_0 n' + \phi_0), \quad n' = 1, 2, ..., N'$$
 (2.2)

where x_1 is the incident wave, x_0 and ϕ_0 are the magnitude and phase of the incident wave. We can derive the re-radiated wave from a nonlinear device for the first, second, and third order harmonics using Eq. (2.1) as

$$s_{1}[n'] = (a_{1}x_{0} + \frac{3}{4}a_{3}x_{0}^{3})\sin(\omega_{0}n' + \phi_{1}) - \frac{1}{2}a_{2}x_{0}^{2}\cos(2\omega_{0}n' + \phi_{2}) - \frac{1}{4}a_{3}x_{0}^{3}\sin(3\omega_{0}n' + \phi_{3})$$
(2.3)

The re-radiated signal, s_1 , can be rewritten by moving the phase information into the amplitudes as

$$s_{1}[n'] = b_{1}\sin(\omega_{0}n') + b_{2}\sin(2\omega_{0}n') + b_{3}\sin(3\omega_{0}n') + b_{4}\cos(\omega_{0}n') + b_{5}\cos(2\omega_{0}n') + b_{6}\cos(3\omega_{0}n')$$
(2.4)

where b coefficients are derived as

$$b_{1} = (a_{1}x_{0} + \frac{3}{4}a_{3}x_{0}^{3})\cos(\phi_{1})$$

$$b_{2} = \frac{1}{2}a_{2}x_{0}^{2}\sin(\phi_{2})$$

$$b_{3} = -\frac{1}{4}a_{3}x_{0}^{3}\cos(\phi_{3})$$

$$b_{4} = (a_{1}x_{0} + \frac{3}{4}a_{3}x_{0}^{3})\sin(\phi_{1})$$

$$b_{5} = -\frac{1}{2}a_{2}x_{0}^{2}\cos(\phi_{2})$$

$$b_{6} = -\frac{1}{4}a_{3}x_{0}^{3}\sin(\phi_{3})$$
(2.5)

As shown in Eq. (2.4), a nonlinear device re-radiates a signal at first, second and third harmonics of the fundamnetal frequency, ω_0 , if driven by a single-tone incident wave. The phase of each harmonic is a random variable taking a value in $[-\pi, \pi]$ interval.

2.1.2 Two-Tone Re-Radiation

In case of a sinusoidal incident wave that contains two distinct frequencies, we have

$$x_{2} = x_{21}\sin(\omega_{1}n' + \phi_{21}) + x_{22}\sin(\omega_{2}n' + \phi_{22}),$$

$$n' = 1, 2, \dots, N'$$
(2.6)

where x_2 is the incident wave, x_{21} and x_{22} are the magnitudes of the wave, ϕ_{21} and ϕ_{22} are the initial phases and *n* is the nth harmonic of the fundamental frequencies, ω_1 and ω_2 . The re-radiated wave from a nonlinear device to a two-tone incident wave contains not only the harmonics of the fundamental frequencies, ω_1 and ω_2 , but also intermodulation products of those frequencies. Using Eq. (2.1) we can calculate the re-radiated wave for the first three harmonics as

$$s_2[n'] = \sum_{n=1}^3 a_n x_2^n = a_1 x_2 + a_2 x_2^2 + a_3 x_2^3$$
(2.7)

First, second and third terms of Eq. (2.7) are calculated as

$$a_1 x_2 = a_1 x_{21} \sin(\omega_1 n' + \phi_1) + a_1 x_{22} \sin(\omega_2 n' + \phi_2)$$
(2.8)

$$a_{2}x_{2}^{2} = a_{2}[x_{21}\sin(\omega_{1}n' + \phi_{21}) + x_{22}\sin(\omega_{2}n' + \phi_{22})]^{2}$$

$$= \frac{a_{2}}{2}x_{21}^{2} + \frac{a_{2}}{2}x_{22}^{2} - \frac{a_{2}}{2}x_{21}^{2}\cos(2\omega_{1}n' + \phi_{3})$$

$$- \frac{a_{2}}{2}x_{22}^{2}\cos(2\omega_{2}n' + \phi_{4})$$

$$- a_{2}x_{21}x_{22}\cos((\omega_{1} + \omega_{2})n' + \phi_{5})$$

$$+ a_{2}x_{21}x_{22}\cos((\omega_{1} - \omega_{2})n' + \phi_{6})$$
(2.9)

$$a_{3}x_{2}^{3} = a_{3}[x_{21}\sin(\omega_{1}n' + \phi_{21}) + x_{22}\sin(\omega_{2}n' + \phi_{22})]^{3}$$

$$= -\frac{a_{3}}{4}x_{21}^{3}\sin(3\omega_{1}n' + \phi_{7}) - \frac{a_{3}}{4}x_{22}^{3}\sin(3\omega_{2}n' + \phi_{8})$$

$$+ (\frac{3a_{3}}{4}x_{21}^{3} + \frac{3a_{3}}{2}x_{22}^{2}x_{21})\sin(\omega_{1}n' + \phi_{1})$$

$$+ (\frac{3a_{3}}{4}x_{22}^{3} + \frac{3a_{3}}{2}x_{21}^{2}x_{22})\sin(\omega_{2}n' + \phi_{2})$$

$$- \frac{3a_{3}}{4}x_{21}^{2}x_{22}\alpha - \frac{3a_{3}}{4}x_{22}^{2}x_{21}\beta$$
(2.10)

where α and β are

$$\alpha = \sin((\omega_2 - 2\omega_1)n' + \phi_9) + \sin((2\omega_1 + \omega_2)n' + \phi_{10})$$

$$\beta = \sin((\omega_1 - 2\omega_2)n' + \phi_{11}) + \sin((2\omega_2 + \omega_1)n' + \phi_{12})$$
(2.11)

The re-radiated signal, s_2 , can be rewritten by moving the phase information into the amplitudes as

$$s_{2}[n'] = c_{1} \sin(\omega_{1}n') + c_{2} \sin(2\omega_{1}n') + c_{3} \sin(3\omega_{1}n') + c_{4} \cos(\omega_{1}n') + c_{5} \cos(2\omega_{1}n') + c_{6} \cos(3\omega_{1}n') + c_{7} \sin(\omega_{2}n') + c_{8} \sin(2\omega_{2}n') + c_{9} \sin(3\omega_{2}n') + c_{10} \cos(\omega_{2}n') + c_{11} \cos(2\omega_{2}n') + c_{12} \cos(3\omega_{2}n') + c_{13} \cos((\omega_{1} + \omega_{2})n') + c_{14} \sin((\omega_{1} + \omega_{2})n') + c_{15} \cos((\omega_{1} - \omega_{2})n') + c_{16} \sin((\omega_{1} - \omega_{2})n') + c_{17} \cos((\omega_{2} - 2\omega_{1})n') + c_{18} \sin((\omega_{2} - 2\omega_{1})n') + c_{19} \cos((2\omega_{1} + \omega_{2})n') + c_{20} \sin((2\omega_{1} + \omega_{2})n') + c_{21} \cos((\omega_{1} - 2\omega_{2})n') + c_{22} \sin((\omega_{1} - 2\omega_{2})n') + c_{23} \cos((2\omega_{2} + \omega_{1})n') + c_{24} \sin((2\omega_{2} + \omega_{1})n')$$

where the *c* coefficients of the first three harmonics of the fundamental frequencies are derived as 2a = 2a

$$c_{1} = (a_{1}x_{1} + \frac{3a_{3}}{4}x_{1}^{3} + \frac{3a_{3}}{2}x_{2}^{2}x_{1})\cos(\phi_{1})$$

$$c_{2} = \frac{a_{2}}{2}x_{1}^{2}\sin(\phi_{3}), c_{3} = -\frac{a_{3}}{4}x_{1}^{3}\cos(\phi_{7})$$

$$c_{4} = (a_{1}x_{1} + \frac{3a_{3}}{4}x_{1}^{3} + \frac{3a_{3}}{2}x_{2}^{2}x_{1})\sin(\phi_{1})$$

$$c_{5} = -\frac{a_{2}}{2}x_{1}^{2}\cos(\phi_{3}), c_{6} = -\frac{a_{3}}{4}x_{1}^{3}\sin(\phi_{7})$$

$$c_{7} = (a_{1}x_{2} + \frac{3a_{3}}{4}x_{2}^{3} + \frac{3a_{3}}{2}x_{1}^{2}x_{2})\cos(\phi_{2})$$

$$c_{8} = \frac{a_{2}}{2}x_{2}^{2}\sin(\phi_{4}), c_{9} = -\frac{a_{3}}{4}x_{2}^{3}\cos(\phi_{8})$$

$$c_{10} = (a_{1}x_{2} + \frac{3a_{3}}{4}x_{2}^{3} + \frac{3a_{3}}{2}x_{1}^{2}x_{2})\sin(\phi_{2})$$

$$c_{11} = -\frac{a_{2}}{2}x_{2}^{2}\cos(\phi_{4}), c_{12} = -\frac{a_{3}}{4}x_{2}^{3}\sin(\phi_{8})$$
(2.13)

The c coefficients are derived for the first three intermodulation products of the fundamental frequencies as

$$c_{13} = -a_2 x_1 x_2 \cos(\phi_5)$$

$$c_{14} = a_2 x_1 x_2 \sin(\phi_5)$$

$$c_{15} = a_2 x_1 x_2 \cos(\phi_6)$$

$$c_{16} = -a_2 x_1 x_2 \sin(\phi_6)$$

$$c_{17} = -\frac{3a_3}{4} x_1^2 x_2 \sin(\phi_9)$$

$$c_{18} = -\frac{3a_3}{4} x_1^2 x_2 \cos(\phi_9)$$
(2.14)

The c coefficients of the next three intermodulation products are

$$c_{19} = -\frac{3a_3}{4} x_1^2 x_2 \sin(\phi_{10})$$

$$c_{20} = -\frac{3a_3}{4} x_1^2 x_2 \cos(\phi_{10})$$

$$c_{21} = -\frac{3a_3}{4} x_2^2 x_1 \sin(\phi_{11})$$

$$c_{22} = -\frac{3a_3}{4} x_2^2 x_1 \cos(\phi_{11})$$

$$c_{23} = -\frac{3a_3}{4} x_2^2 x_1 \sin(\phi_{12})$$

$$c_{24} = -\frac{3a_3}{4} x_2^2 x_1 \cos(\phi_{12})$$
(2.15)

As shown in Eq. (2.12), the re-radiated signal from a nonlinear circuit to the two-tone incident wave from Eq. (2.6) contains ω_1 , ω_2 , $2\omega_1$, $2\omega_2$, $3\omega_1$ and $3\omega_2$ frequencies and mixing products of those frequencies, $\omega_1 + \omega_2$, $\omega_1 - \omega_2$, $\omega_2 - 2\omega_1$, $2\omega_1 + \omega_2$, $\omega_1 - 2\omega_2$, and $2\omega_2 + \omega_1$. The phases of harmonics and intermodulation products are random variables taking a value in $[-\pi, \pi]$ interval.

The experimental design and simulation of various electronic devices using NI AWR Design Environment are given in the next section. The output powers of the circuits under test are gathered form AWR at first three harmonics and utilized to calculate b coefficients in Eq. (2.5) and c coefficients in Eq. (2.13), Eq. (2.14), and Eq. (2.15).

2.2 Design and Simulation

Three main circuit types, namely diode clamper, diode limiter and full wave rectifier, have been designed using National Instruments (NI) AWR Design Environment to gather a data set of different realizations for both single-tone and two-tone re-radiation cases. Fig. 2.1 shows the diode clamper circuit under test. A simple diode clamper circuit consists of a capacitor, a diode, and a resistor that shifts the signal to a desired DC level.



Figure 2.1: Schematic of Device Type 1, Diode Clamper Circuit, Designed Using National Instruments (NI) AWR Design Environment.

The second type of the circuits under test, diode limiter, is shown in Fig. 2.2. A basic diode limiter circuit is generally used to limit the input voltage. A full-wave rectifier Circuit is also designed using AWR design environment, as shown in Fig. 2.3, to collect a large data set. An Ideal Transformer with Center Tap (XFMRTAP) is used in the circuit. The Swept Variable Control (SWPVAR) is used to sweep certain parameters with 90 different values for each circuit type which gives 270 electronic circuits under test in total. As a novel method, the transmitted power is swept from 0 to 40 dBm with 1 dB intervals at 1 GHz frequency for each circuit to capture the nonlinear I-V characteristics of the nonlinear junctions within the circuits under test.



Figure 2.2: Schematic of Device Type 2, Diode Limiter Circuit, Designed Using National Instruments (NI) AWR Design Environment.

third order harmonics.

Realistic electronic circuits are simulated using AWR Design Environment to create a real life scenario in this study. The harmonic power levels at the first, second and third harmonics are simulated using AWR Microwave Office Harmonic Balance simulator. Then, the received powers of the electronic circuits under test are analyzed to enable the performance assessment of the proposed technique. The novel approach in this



Figure 2.3: Schematic of Device Type 3, Full-Wave Rectifier Circuit, Designed Using National Instruments (NI) AWR Design Environment.

thesis can be applied for any other type or number of nonlinear electronic circuits outside this research as well.

The proposed linear model in the next chapter relates the measurements to the vectors of unknown parameters. Next, the statistical features of the normalized estimated vectors of parameters are used as test and training data in classification of ECUT for both single-tone and two-tone re-radiation cases.



3. LINEAR MODEL

3.1 Model Description

A linear model is developed in this section to relate the AWR measurements to the unknown deterministic vectors of parameters characterizing the nonlinearities of the ECUT. According to the proposed linear model, the received data vector \mathbf{r} can be written as,

$$\mathbf{r} = \mathbf{H}\boldsymbol{\theta} + \mathbf{w} \tag{3.1}$$

where

- **H** ∈ ℂ^{N×p} is a known full rank matrix whose columns span the useful signal subspace H;
- θ ∈ C^{p×1} is an unknown deterministic vector of parameters accounting for the signal location in H;
- w denotes the CWGN contributions which are assumed to be independent and identically distributed (iid), complex normal random vectors with zero-mean and covariance matrix $\mathbf{C} = \sigma^2 \mathbf{I}$.
- *p* dimension gives the number of harmonics of fundamental frequencies and intermodulation products of those frequencies which reduces to "6" for single-tone re-radiation case and "24" for two-tone re-radiation since we only consider the first three harmonics.

The re-radiated signal to a single-tone incident wave contains no intermodulation terms. The re-radiated signals in Eq. (2.4) and Eq. (2.12) are re-written based on

the proposed linear model as

$$s_1[n'] = \mathbf{H}_1 \boldsymbol{\theta}_1$$

$$s_2[n'] = \mathbf{H}_2 \boldsymbol{\theta}_2$$
(3.2)

where the re-radiated waves, s_1 and s_2 , are written as the product of observation matrices, \mathbf{H}_1 and \mathbf{H}_2 , and vectors of unknown parameters, θ_1 and θ_2 , for single-tone and two-tone re-radiation cases, respectively.

The transmitted powers are swept within a determined range to capture the nonlinear behaviors of electronic circuits in this study. The CWGN contributions in Eq. (3.1) are swept along with the transmitted powers. By sweeping the noise vector along with varying power, we are adding a corresponding noise value (proportional to the swept power) to the re-radiated wave vectors in Eq. (3.2).

3.2 Observation Matrices and Vectors of Unknown Parameters

Each nonlinear circuit under test has a distinct response (θ 's) to a single-tone or two-tone time-varying incident wave with varying power. As a result, a unique unknown deterministic vector of parameters can be estimated from the proposed linear model for each ECUT which makes each device distinguishable from other nonlinear devices. The observation matrices and vectors of unknown parameters are derived in two subsections for both single-tone and two-tone re-radiation cases at first, second, and third order harmonics.

3.2.1 Single-Tone Re-Radiation

The $\mathbf{H}_1^{N \times 6}$ matrix and $\theta_1^{6 \times 1}$ vector (index 1 represents the single-tone re-radiation case) are derived from Eq. (2.4) for single-tone re-radiation case at first, second and third harmonics of the fundamental frequency, ω_0 , as

$$\boldsymbol{\theta}_1 = \left[\begin{array}{cccc} b_1 & b_2 & \dots & b_5 & b_6 \end{array} \right]^T \tag{3.3}$$

$$\mathbf{H}_{1} = \begin{bmatrix} \sin(\omega_{0}) & \dots & \sin(3\omega_{0}) & \dots & \cos(3\omega_{0}) \\ \sin(2\omega_{0}) & \dots & \sin(6\omega_{0}) & \dots & \cos(6\omega_{0}) \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ \sin(N'\omega_{0}) & \dots & \sin(3N'\omega_{0}) & \dots & \cos(3N'\omega_{0}) \end{bmatrix}$$
(3.4)

The θ_1 vector in Eq. (3.3) contains the phase information of the re-radiated signal in Eq. (2.4). Each nonlinear circuit under test possesses a distinct vector of parameters that makes it separable form other electronic circuits.

3.2.2 Two-Tone Re-Radiation

The $\mathbf{H}_2^{N \times 24}$ matrix and $\theta_2^{24 \times 1}$ vector (index 2 represents the two-tone re-radiation case) are similarly derived from Eq. (2.12) for two-tone re-radiation case at first three harmonics of the fundamental frequencies, ω_1 and ω_2 , and intermodulation products of those frequencies as

$$\boldsymbol{\theta}_2 = \begin{bmatrix} c_1 & c_2 & \dots & c_{23} & c_{24} \end{bmatrix}^T \tag{3.5}$$

$$\mathbf{H}_{2} = \begin{bmatrix} \sin(\boldsymbol{\omega}_{1}) & \dots & \cos(\boldsymbol{\omega}_{2}) & \dots & \sin(2\boldsymbol{\omega}_{2} + \boldsymbol{\omega}_{1}) \\ \sin(2\boldsymbol{\omega}_{1}) & \dots & \cos(2\boldsymbol{\omega}_{2}) & \dots & \sin(4\boldsymbol{\omega}_{2} + 2\boldsymbol{\omega}_{1}) \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ \sin(N'\boldsymbol{\omega}_{1}) & \dots & \cos(N'\boldsymbol{\omega}_{2}) & \dots & \sin(2N'\boldsymbol{\omega}_{2} + N'\boldsymbol{\omega}_{1}) \end{bmatrix}$$
(3.6)

The θ_2 vector in Eq. (3.5) contains the phase information of the re-radiated signals in Eq. (2.12). Similar to single-tone re-radiation case, a unique vector of parameters can be derived for each nonlinear circuit under test that makes it distinguishable form other electronic circuits under test.

3.3 Maximum Likelihood Estimation

Maximum Likelihood Estimation is considered to be the most popular approach to obtaining practical estimators. The performance of the MLE is optimal for large enough data sets. The goal of maximum likelihood estimation is to find the parameter values that give the distribution that maximizes the probability of observing the data [47]. The probability density function (PDF) of the received data formulated in Eq.(3.1) is

$$p(\mathbf{r};\boldsymbol{\theta}) = \frac{1}{\pi^N \sigma^{2N}} exp\left[-\frac{1}{\sigma^2} (\mathbf{r} - \mathbf{H}\boldsymbol{\theta})^H (\mathbf{r} - \mathbf{H}\boldsymbol{\theta}) \right].$$
(3.7)

The maximum likelihood estimation of θ is the value that maximizes the PDF in Eq.(3.7). In other words, MLE of θ is the value that minimizes the Least Squares (LS) error

$$\mathbf{J} = (\mathbf{r} - \mathbf{H}\boldsymbol{\theta})^{H} (\mathbf{r} - \mathbf{H}\boldsymbol{\theta}).$$
(3.8)

We want to find the value of θ that minimizes **J** [47], so we can write

$$\mathbf{J} = \mathbf{r}^{H}\mathbf{r} - \mathbf{r}^{H}\mathbf{H}\theta - \theta^{H}\mathbf{H}^{H}\mathbf{r} + \theta^{H}\mathbf{H}^{H}\mathbf{H}\theta$$
(3.9)
$$\frac{\partial \mathbf{J}}{\partial \theta} = -(\mathbf{H}^{H}\mathbf{r})^{*} + (\mathbf{H}^{H}\mathbf{H}\theta)^{*}$$
$$= -\left[\mathbf{H}^{H}(\mathbf{r} - \mathbf{H}\theta)\right]^{*}.$$
(3.10)

We can find the minimizing solution by setting the complex gradient equal to zero [47], yielding the MLE

$$\hat{\boldsymbol{\theta}} = (\mathbf{H}^H \mathbf{H})^{-1} \mathbf{H}^H \mathbf{r}.$$
(3.11)

The MLE above has been used in MATLAB simulations to estimate the unknown deterministic vectors of parameters in Eq.(3.3) and Eq.(3.5) in the presence of Complex White Gaussian Noise (CWGN) for different SNR values using Monte Carlo simulations. In this study, Monte Carlo simulation involves 1000 recalculations before it is complete.

The performance of the estimator is evaluated by plotting the Mean Square Error (MSE) functions with respect to SNR values for diode clamper circuits under test. As it is shown in Fig. 3.1, MSE functions of the estimator at first, second and third order harmonics of ω_0 frequency are descending as the SNR value increases for single-tone re-radiation case at 1mW transmitted power. As it appears from Fig. 3.1, MSE is almost zero when SNR value is greater than - 5 dB. The estimation of the unknown



Figure 3.1: MSE Functions of the MLE for Device Type 1, Diode Clamper Circuits, First Three Harmonics of The Fundamental Frequency, Single-Tone Re-radiation.

vectors of parameters is done at $SNR = 5 \, dB$ for both single-tone and two-tone cases in this study. The MLE shows a better performance during estimation for single-tone re-radiation compared to the two-tone case.

3.4 K-Nearest Neighbors Classification

Classification of the ECUT is done in this study using a 3-Nearest Neighbor classifier that is trained to use the normalized estimated vectors of unknown parameters as test and training data sets. Training data is gathered from National Instruments (NI) AWR Design Environment by designing various nonlinear electronic circuits under test to create a more realistic scenario. In this classification, 70% of the data is allocated for training and 30% for testing. We label each row of training data set with a device class. KNN classifier finds the 3 nearest neighbors by calculating the Euclidean distances between the test and training data. The test data is assigned to one of the three types of devices under test by deriving the smallest Euclidean distances. The Euclidean distances are given in Table 3.1 for single-tone re-radiation case. As it appears from Table 3.1, the within class distances (diagonal elements) for both mean and variance of the estimated vectors are small, whereas the between class distances (non-diagonal elements) are high. This means that the estimated vectors of the circuits in the same

		Diode	Diode	Full Wave	
		Clamper	Limiter	Rectifier	
	Diode	0.52	2 4 2	16.3	
	Clamper	0.52	5.42		
Maan	Diode	3.42	0.46	12.01	
wiean	Limiter	5.42	0.40	12.91	
	FullWave	16.3	12.01	0.41	
	Rectifier	10.5	12.91	0.41	
	Diode	26.2	112.4	452.27	
	Clamper	20.5	115.4	432.37	
Variance	Diode	113.4	23.25	220.02	
	Limiter	113.4	23.23	559.02	
	FullWave	452.37	330.02	12 20	
	Rectifier	452.57	559.02	14.47	

 Table 3.1: Euclidean Distances for Single-Tone Re-Radiation Case

class have minimum distance from each other and maximum distance from the other types of circuits in harmonic space. As a result, these unique vectors are proven to be useful for distinguishing electronic devices. The accurate simulation results prove our proposed method to be efficient for classification of ECUT especially at low SNR values in more realistic scenarios.

4. PERFORMANCE EVALUATION AND SIMULATION RESULTS

The performance assessment of the presented approach for classification of various electronic devices is presented in this chapter. Simulation results are analyzed in two subsections for single-tone and two-tone re-radiation cases. In each subsection, we present the scattered feature plots of the normalized estimated vectors of parameters. Then, we discuss the corresponding classification results by presenting the confusion matrices. The kNN classification method is used in both subsections as classification technique. As described earlier in Chapter 2, first three harmonics of the received powers are collected from AWR design environment for electronic circuits in Fig. 2.1, Fig. 2.2 and Fig. 2.3. Then, the proposed linear model in Chapter 3 relates the data to the unknown deterministic vectors of parameters. These vectors are unique for each nonlinear circuit under test which makes them distinguishing factors to be used in classification of nonlinear devices.

Maximum likelihood estimation of the vectors of parameters is done in the presence of Complex White Guassian Noise (CWGN) at different SNR values in Chapter 3.3. The estimated data is normalized using Z-Score Normalization Method. The basic z-score formula for a sample is $x = \bar{x}$

$$Z = \frac{x - \bar{x}}{S} \tag{4.1}$$

where x is the sample data, \bar{x} denotes the sample mean, and S is the sample standard deviation. Furthermore, the estimation and classification steps are repeated through 1000 Monte Carlo trials to make sure that the method can be applied to real life scenarios. Next, the statistical features of the normalized estimated vectors of parameters are used as test and training data sets in classification of electronic circuits under test.



Figure 4.1: Scattered Feature Plots of The Normalized Estimated Vectors of Parameters at SNR = 5 dB, First Three Harmonics of ω_0 frequency, Single-Tone Re-Radiation Case, (a) Mean, (b) Variance.

4.1 Single-Tone Re-Radiation Results

The performance of the 3-NN classifier is evaluated for single-tone re-radiation case in this section. The 3D scattered feature plots of the normalized estimated vectors of parameters are shown in Fig. 4.1 for single-tone re-radiation case with first, second and third order harmonics defined as dimensions of harmonic space. As shown in Figure 4.1(a) and 4.1(b), the statistical features of the normalized estimated vectors are well clustered for the first three harmonics of ω_0 frequency. As a result, these features are utilized to classify nonlinear devices using Euclidean distances and kNN classification technique described in Chapter 3.4. The classification of ECUT is repeated through 1000 Monte Carlo simulations. The confusion matrices in Table 4.1 show the simulated classification results at SNR = 5 dB for single-tone re-radiation

Table 4.1: Confusion Matrices at First Three Harmonics of ω_0 Frequency for Single-Tone Re-Radiation Case

		Device 1 Device 2		Device 3
	Device 1	99%	1%	0%
Mean	Device 2	1.2%	98.8%	0%
	Device 3	0%	0%	100%
		Device 1	Device 2	Device 3
	Device 1	92.6%	7.4%	0%
Variance	Device 2	1.3%	98.7%	0%
	Device 3	0%	0%	100%



Figure 4.2: Scattered Feature Plots of The Normalized Estimated Vectors of Parameters at SNR = 5 dB, First Three Harmonics of ω_1 frequency, Two-Tone Re-Radiation Case, (a) Mean, (b) Variance.

case at first three harmonics of ω_0 frequency. As it is clear in Table 4.1, ECUT are successfully classified with less than 1.3% confusion percentage between three classes when mean of the normalized estimated vectors are used as test and training data. The confusion percentage stays under 7.5% when variance of the normalized estimated data is used for classification. Device type 3, full-wave rectifier circuit, is classified with zero confusion percentage.

4.2 Two-Tone Re-Radiation Results

The performance of the 3-NN classifier is evaluated for two-tone re-radiation case in this section. The scattered feature plots of the normalized estimated vectors of Table 4.2: Confusion Matrices at First Three Harmonics of ω_1 Frequency for Two-Tone Re-Radiation Case

		Device 1	Device 2	Device 3
	Device 1	100%	0%	0%
Mean	Device 2	0%	100%	0%
	Device 3	0%	0%	100%
		Device 1	Device 2	Device 3
	Device 1	100%	0%	0%
Variance	Device 2	0%	100%	0%
	Device 3	0%	0%	100%



Figure 4.3: Scattered Feature Plots of The Normalized Estimated Vectors of Parameters at SNR = 5 dB, First Three Harmonics of ω_2 frequency, Two-Tone Re-Radiation Case, (a) Mean, (b) Variance.

unknown parameters at first three harmonics of ω_1 frequency are given in Fig. 4.2. As shown in Fig. 4.2(a) and 4.2(b), the mean and variance of the normalized estimated data are well-separated in harmonic space for the first three harmonics of ω_1 frequency in two-tone re-radiation case. Corresponding confusion matrices are given in Table 4.2. As shown in Table 4.2, all three device classes are classified at first, second, and third harmonics of ω_1 frequency with 100% classification percentage and zero confusions. This result is expected since estimated data is well-clustered in Fig. 4.2.

The feature plots of the first three harmonics of ω_2 frequency shown in Fig. 4.3(a) and 4.3(b) are fairly separated. The confusion percentages at first three harmonics of ω_2 frequency are given in Table 4.3. Confusion percentage stays under 0.3% when mean of the normalized estimated data is utilized in classification and 4.3% when variance Table 4.3: Confusion Matrices at First Three Harmonics of ω_2 Frequency for Two-Tone Re-Radiation Case

		Device 1	Device 2	Device 3
	Device 1	99.8%	0.2%	0%
Mean	Device 2	0%	100%	0%
	Device 3	0%	0%	100%
		Device 1	Device 2	Device 3
	Device 1	95.8%	4.2%	0%
Variance	Device 2	1.4%	98.6%	0%
	Device 3	0%	0%	100%



Figure 4.4: Scattered Feature Plots of The Normalized Estimated Vectors of Parameters at SNR = 5 dB, First Three Intermodulation Frequencies, Two-Tone Re-Radiation Case, (a) Mean, (b) Variance.

of the normalized estimated vectors is used as test and training data.

The scattered feature plots and confusion matrices at intermodulation products of fundamental frequencies are also presented for further evaluation of the approach. The 3D feature plots of the first three intermodulation frequencies, $\omega_1 + \omega_2, \omega_1 - \omega_2$, and $\omega_2 - 2\omega_1$, defined as dimensions of harmonic space are presented in Fig. 4.4. The corresponding confusion matrices are given in Table 4.4. As it appears in Fig. 4.4(a), the mean of the normalized estimated vectors are closely spaced for each one of the three device classes. Therefore, the devices under test are classified with zero confusion between three classes as shown in Table 4.4. Confusion percentage stays under 0.5% in Table 4.4 when variance of the estimated data is used at first three intermodulation frequencies. Feature plots of the next three intermodulation

Table 4.4: Confusion Matrices at First Three Intermodulation Frequencies forTwo-Tone Re-Radiation Case

		Device 1	Device 2	Device 3
	Device 1	100%	0%	0%
Mean	Device 2	0%	100%	0%
	Device 3	0%	0%	100%
		Device 1	Device 2	Device 3
	Device 1	99.9%	0.1%	0%
Variance	Device 2	0.4%	99.6%	0%
	Device 3	0%	0.1%	99.9%



Figure 4.5: Scattered Feature Plots of The Normalized Estimated Vectors of Parameters at SNR = 5 dB, Second Three Intermodulation Frequencies, Two-Tone Re-Radiation Case, (a) Mean, (b) Variance.

frequencies, $2\omega_1 + \omega_2$, $\omega_1 - 2\omega_2$ and $2\omega_2 + \omega_1$, are shown in Fig. 4.5. Unlike feature plots at first three intermodulation frequencies, statistical features of the normalized estimated data in Fig. 4.5(a) and 4.5(b) are poorly clustered. The corresponding classification results in Table 4.5 show that the three classes are not as well-clustered as the first three harmonics and intermodulation frequencies. Despite the fact that scattered data is noisier than the data at other frequencies, confusion percentage stays under 6.9% when mean of the normalized estimated vectors is used in classification as shown in Table 4.5. The performance of the classifier drops to 66.6% for device type

Table 4.5: Confusion Matrices at Second Three Intermodulation Frequencies forTwo-Tone Re-Radiation Case

		Device 1	Device 2	Device 3
	Device 1	93.2%	6.8%	0%
Mean	Device 2	4.4%	93.5%	2.1%
	Device 3	0%	1%	99%
		Device 1	Device 2	Device 3
	Device 1	74.4%	25%	0.6%
Variance	Device 2	20.7%	66.6%	12.7%
	Device 3	1%	9.7%	89.3%

2 with 12.7% and 20.7% confusion percentages. Maximum confusion percentages are 25% for device type 1 and 9.7% for device type 3. The performance of the classifier improves as the SNR value increases.

The 3-NN classifier shows its best performance when estimation and classification steps are done at first three harmonics of ω_1 frequency in two-tone re-radiation case as shown in Table 4.2 and Fig.4.2. The vectors of parameters in Eq.(3.3) and Eq.(3.5) have been converted to 3-by-1 and 12-by-1 vectors respectively by moving the phase information into **H**₁, and **H**₂ matrices from Eq.(3.4) and Eq.(3.6) for each nonlinear circuit under test before plotting scattered feature plots and simulating confusion matrices.

Classification of 5 electronic devices in [38], presents promising results, which are given in Table 4.6. Received powers are collected with respect to frequency using sixteen receiver antennas. Mean, standard deviation, minimum and maximum values of the gathered data set are utilized as statistical features using a 3-Nearest Neighbors classifier. Unlike [38], power-swept signals are used as incident waves to

 Table 4.6: Classification Results in [38] for Five Electronic Devices

Device	1	2	3	4	5
Mean	100%	99.4%	88.7%	99%	89.6%
Std. Dev.	0%	1.1%	4.6%	1.4%	4.8%
Min	100%	95.2%	73.8%	92.9%	71.4%
Max	100%	100%	100%	100%	100%

electronic devices and harmonic responses of the devices are analyzed at first three harmonics in this thesis. Multiple receiver antennas in [38] provide spatial diversity, while power-swept signals provide signal-power diversity in this study. Besides, the statistical features of the normalized estimated vectors of unknown parameters are used as distinguishing factors in this research. Presented classification results prove the proposed method in this thesis to be a practical approach for classification of nonlinear devices with a better performance compared to existing classifiers.



5. CONCLUSIONS AND FUTURE WORK

The novel method presented in this paper classifies various nonlinear electronic circuits such as diode clamper, diode limiter and full-wave rectifier using harmonic radar based on a newly proposed linear model and estimation of unknown deterministic vectors of parameters. Harmonic responses of the circuits are simulated and collected as a large data set using National Instruments (NI) AWR Design Environment. This novel technique, derives the harmonic responses of the ECUT using Power Series Model.

As a major continuation, the measurements are related to the unknown vectors of parameters using a newly developed linear model. A unique vector of parameters is estimated using a MLE for each nonlinear circuit under test which allows us to have the unique signature of each one of the Electronic Circuits Under Test (ECUT). The statistical features of the normalized estimated vectors of parameters are analyzed at harmonic frequencies to be used as distinguishing features in classification.

As a novel approach, the classification of the ECUT is done using k-Nearest Neighbors (kNN) classification technique for both single-tone and two-tone re-radiation cases with power-swept incident waves to capture the nonlinearity of the circuits. Performance of the classifier is evaluated for noisy test and training data sets to create a real life scenario. The confusion matrices and scattered feature plots of the normalized estimated data are presented to evaluate the classification technique. Simulation results show that electronic devices under test are successfully classified when statistical features of the normalized estimated vectors of parameters are used for classification. The 3-NN classifier shows its best performance when estimation and classification estimates are done at first three harmonics of ω_1 frequency in two-tone re-radiation case.

Simulation results prove the proposed approach of power-swept incident waves with

unique estimated vectors of unknown parameters to be very effective for classification of nonlinear targets of interest for both single-tone and two-tone re-radiation cases. It is shown that the presented classifier in this study has a better performance compared to existing classifiers.

The proposed technique of this study classifies the ECUT with zero confusion percentages and 100% classification results in some cases. These results may be only obtainable for the electronic circuits that are specifically designed for this research and drop for a different set of electronic circuits outside this work. Taking the statistical feature values (mean and variance) of the estimated data contributes to the high classification results. Other contributing factors may be the made assumptions on CWGN noise vectors in maximum likelihood estimation. The process can be repeated in future work for a different case study with correlated noise vectors. In addition, data can be collected with experimental setup from different nonlinear electronic circuits to verify the results in a more realistic scenario. Furthermore, the performance of the estimator and classifier can be analyzed for fourth, fifth or higher order harmonics of the fundamental frequencies.

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